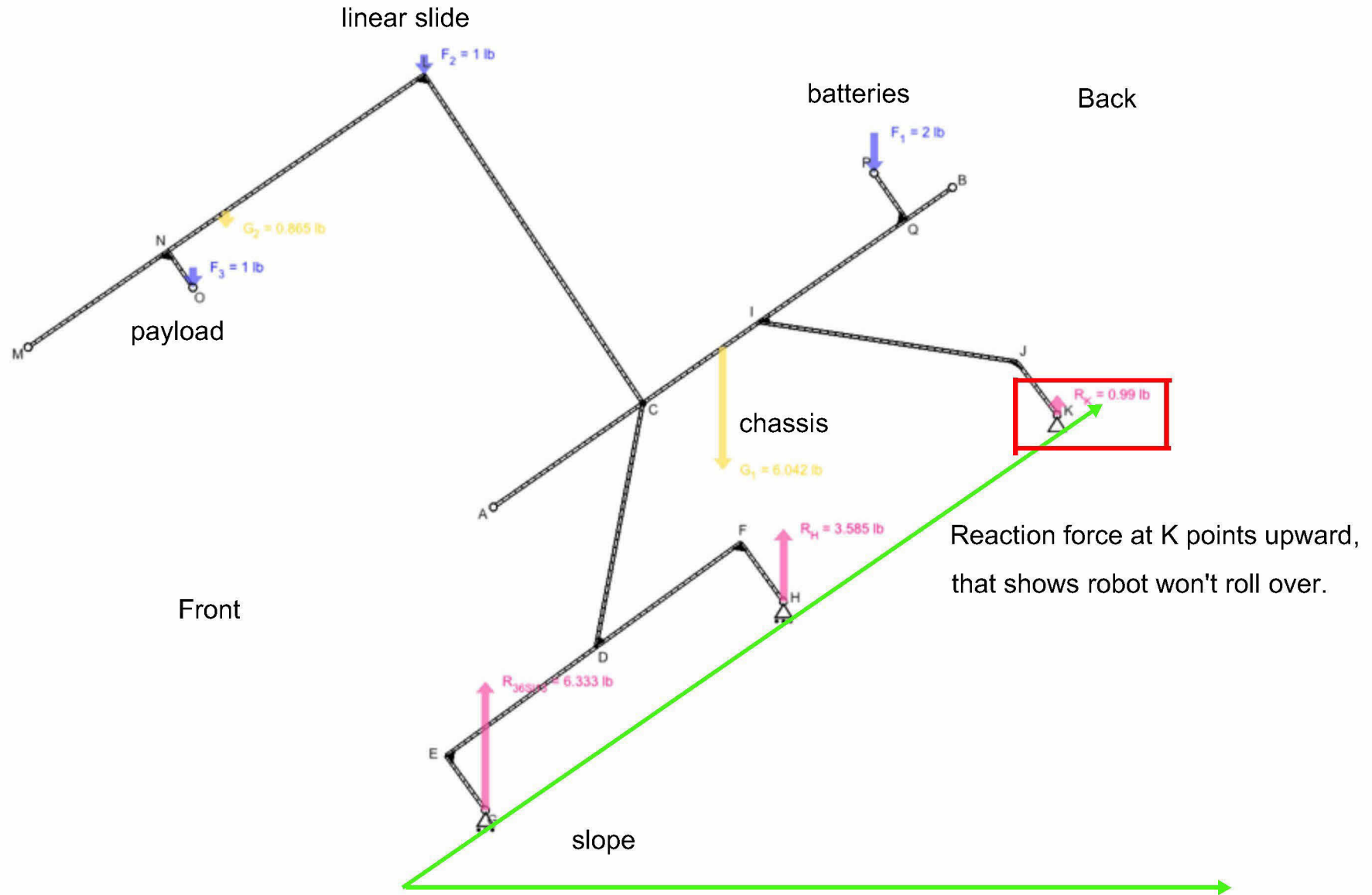


Side view of robot



Robot tilts downward 35 degree and computes reaction force on wheels (G, H and K)