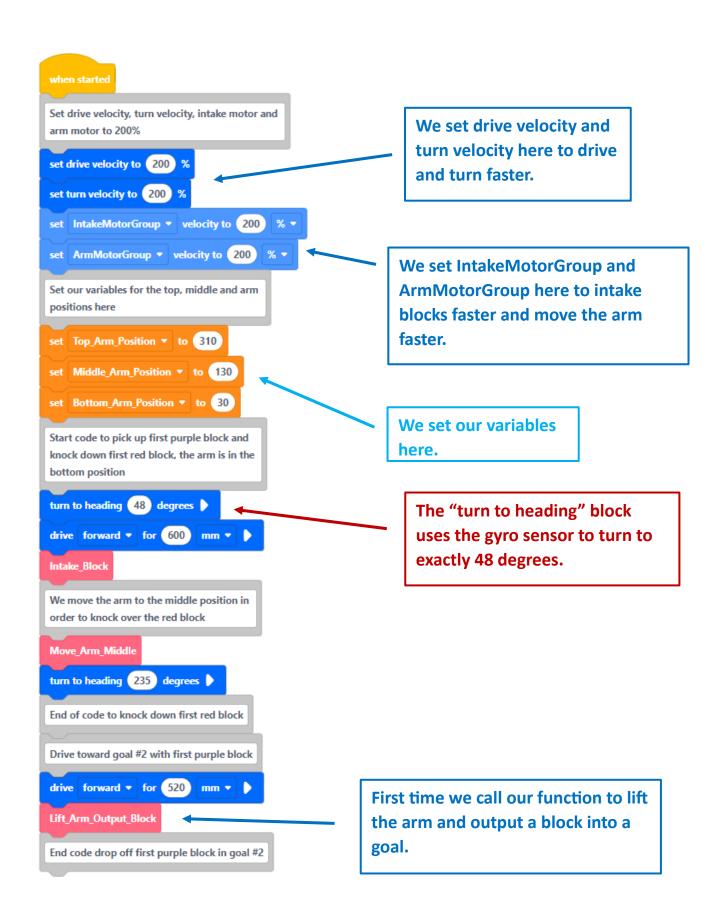
## **VEXcode VR Skills Challenge - Elementary School**

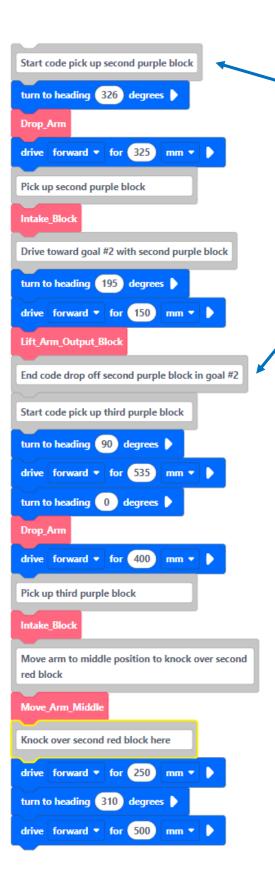
## Title: Autonomous Robohuskies: Navigating into the Future!

Students: Vesper and Hans

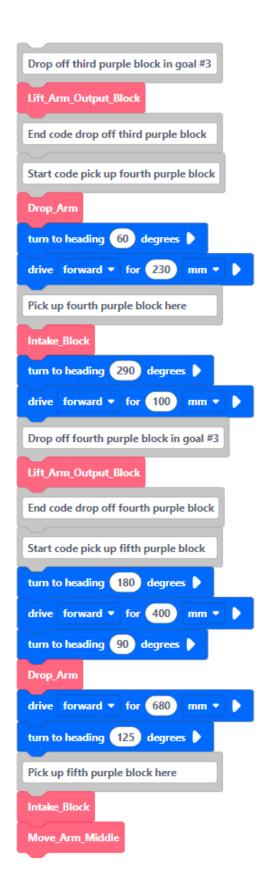
Team number: 97793B (Hicks Team B)

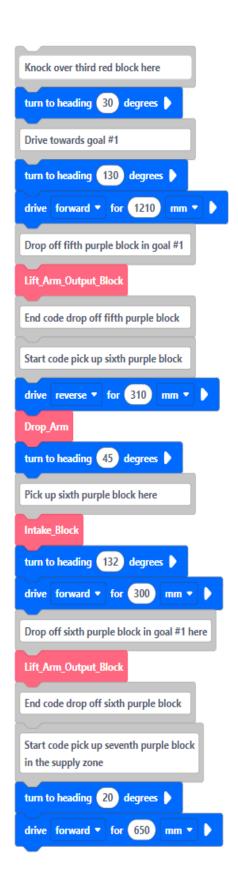
Location: Irvine, CA





These inline comments help us find where a problem is happening, so we know where to fix our code. So, if we see a problem when the robot is picking up the second purple block, the problem must be in between these two comment blocks.





```
Drop_Arm

wait 1 seconds

Intake_Block

turn to heading 180 degrees 

drive forward  for 400 mm  

Lift_Arm_Output_Block

drive reverse  for 400 mm  

Extend the arm into the goal to partial park here

spin ArmMotorGroup  to position 1450 degrees
```

## **Functions:**

