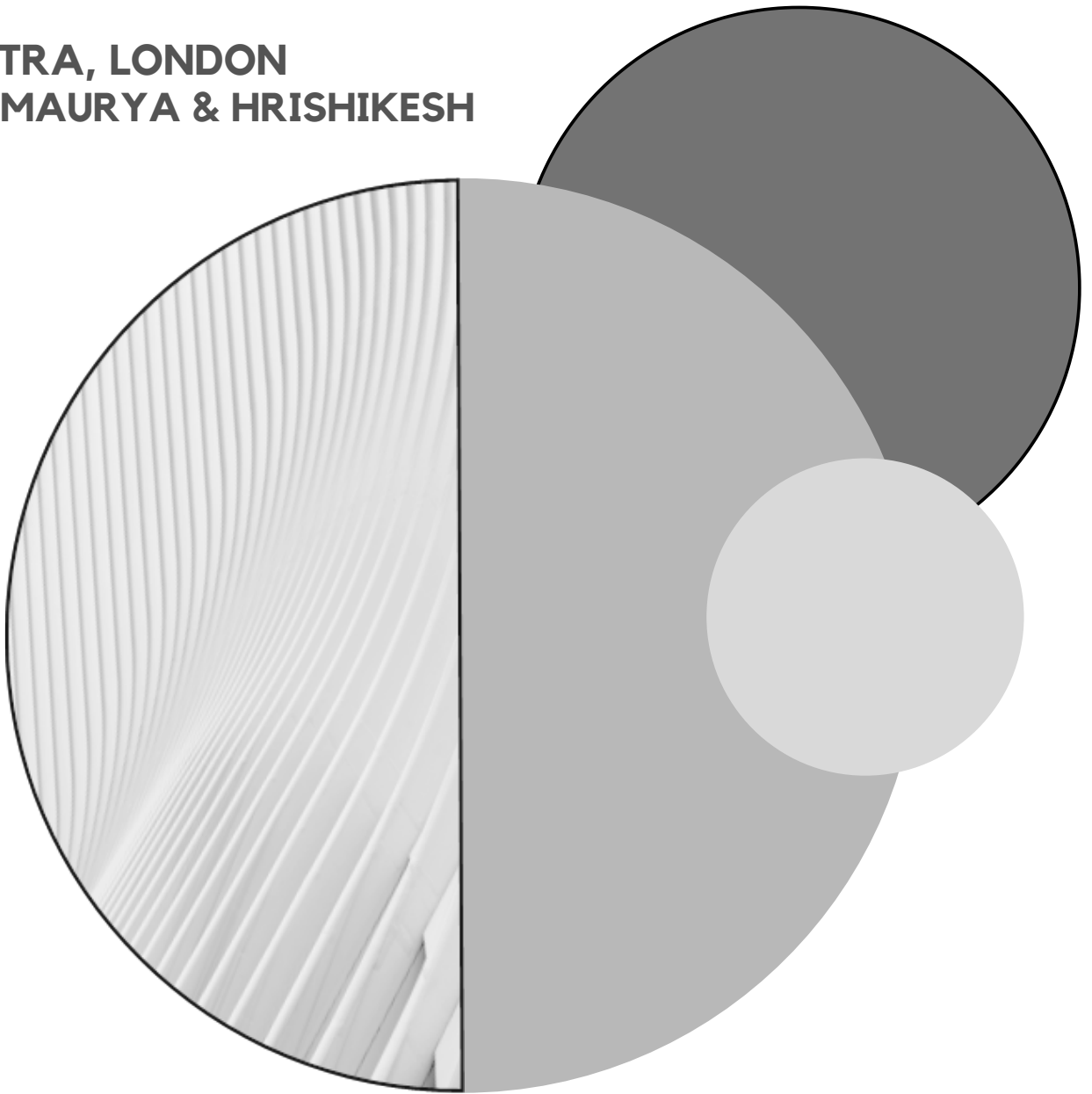


 **20785B**

**TEAM ASTRA, LONDON  
KESHAV, MAURYA & HRISHIKESH**

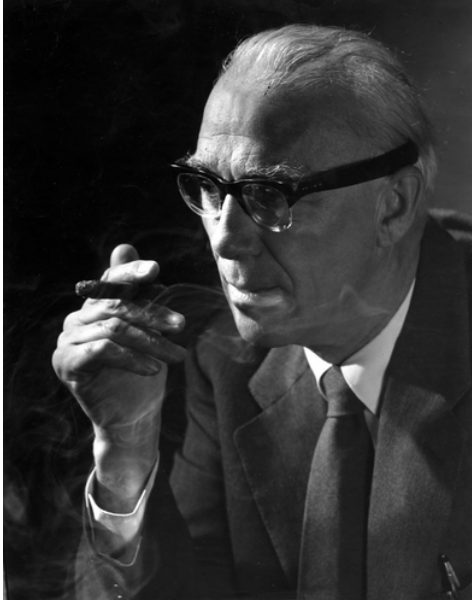


# **ARUP**

## **CAREER READINESS CHALLENGE**

**WORD COUNT : 1000 (EXCLUDING ALL TITLES AND  
SUBTITLES, PICTURES AND PICTURE CAPTIONS - ALL IN  
RED) CONTENT (BLACK)**

# WHY ARCHITECTURE? WHY ARUP?



Sir Ove Arup, founder of ARUP

Architecture shapes our world today. Architecture is currently developing, from skyscrapers to domestic dwellings to large-scale marvels. It must now suit the client's objectives and perform its purpose while also being visually appealing and balancing the needs with the influence on the environment and landscape. This is a fascinating challenge that we hope to learn more about and contribute to in the future, which is why we selected architecture.

Arup is a building business that is a pioneer in the field of sustainability and innovation, as well as a significant leader in addressing environmental issues.



We wanted to explore ARUP and architecture because of Arup's Journey and its wide reaching impact on architecture, as well as its innovative approach to corporate structure. In order to learn more, we contacted Karan Dewnani, a Project Manager at Arup, and were fortunate enough to schedule a meeting.

# DESIGN PROCESS OVERVIEW

The purpose of any design process is to lay down a foundation for a team to follow in order to achieve key objectives.

The RIBA Plan of work which guides Arup and the engineering design process which all engineered products follow, is very similar to our design process. The core factors of each design process are shown clearly and are both relatively alike, although the end goals for each of us are completely different.

## Team 20785B : Design process

TEAM ASTRA PRESENT

### THE ASTRA DESIGN PROCESS V2.0

This step includes researching different methods of creating a mechanism using other teams, vex forums, etc.

**RESEARCHING IDEAS**



**SETTING THE BRIEF**

This involves learning about the game and setting targets for what each mechanism must, should and could be able to do.

Once the idea is chosen, we finalise certain aspects of the design such as placement.

**FINALISING IDEA**



**EVALUATING IDEAS**

Once we have a catalogue of ideas, each idea is evaluated for its benefits and disadvantages, and one idea is chosen.

This stage involves using the CAD design to guide us on how to build the final design.

**BUILDING DESIGN**



**DESIGNING AND VISUALISING IDEAS**

Using CAD software and sketches, we visualise the final product that we will build.

If there are any flaws or improvements that are found during the testing phase, we optimize the initial design.

**IMPROVING**



**TESTING**

Testing includes testing that all systems work as they are intended, as well as ensuring that they work consistently



# ENGINEERING DESIGN PROCESS

Define The Problem

Brainstorm Possible Solutions

Communicate The Results

Research Ideas / Explore Possibilities

Create The Solution

Establish Criteria And Constraints

Refine The Design

Consider Alternative Solutions

Test And Evaluate

Make A Model Or Prototype

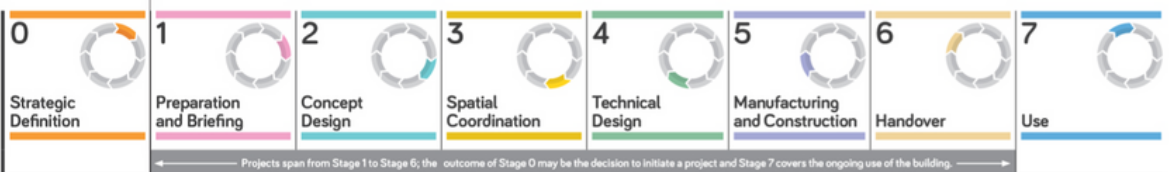
Select An Approach

Develop A Design Proposal



RIBA  
Plan of Work  
2020

The RIBA Plan of Work organises the process of briefing, designing, delivering, maintaining, operating and using a building into eight stages. It is a framework for all disciplines on construction projects and should be used solely as guidance for the preparation of detailed professional services and building contracts.





# DEFINE THE PROBLEM

To define a problem is to simplify it into series of simple steps that must be completed in order to solve it.

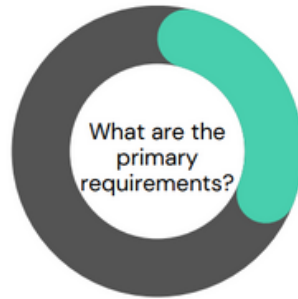


'Human Centric'



Arup's first step as a organisation is to understand and empathize with a client's problem. The first step must be '**client centric**' as Karan put it, understanding the problem the client faces and their need is essential and then it must be broken down and combined with existing primary and secondary data points to help map the project destinations and create a design brief.

Arup ensures the definition of the problem is client centric, breaks the problem down into a design brief



Arup using parallel thinking and the '**Six Thinking Hats**' Methodology to brainstorm by Edvard.



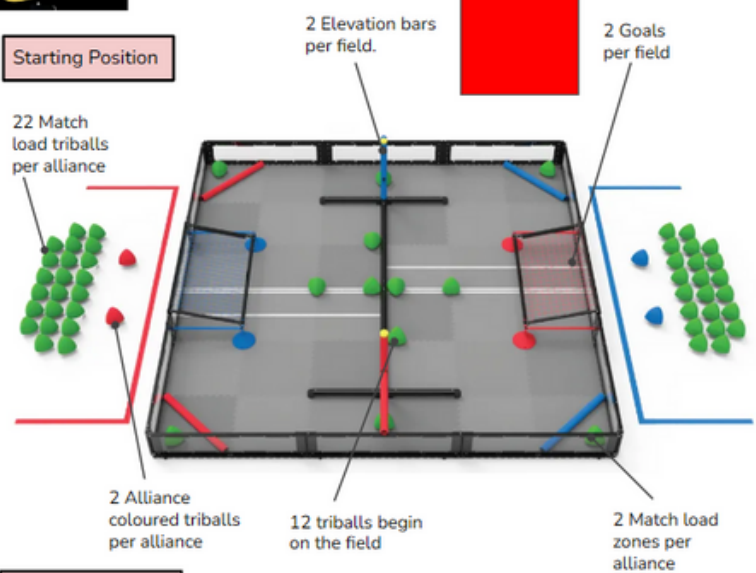
Arup divides the crew into multiple small groups to facilitate parallel thinking. Each group can focus on a small subset of stakeholders, approaching and building a solution based on their priorities while protecting their interests. These ideas follow an initial concept note that is distributed to all stakeholders and internal teams and identifies the primary issue with the new infrastructure. Sir Ove Arup was a firm believer in brainstorming, and the Sydney Opera House featured 12 prototype sail designs.



EDWARD DE BONO'S THEORY



# Understanding the Game Elements



## Game Elements - Triballs

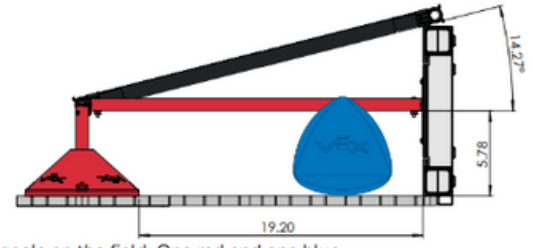


- There are a total of 60 possible triballs on one field.
  - There are 54 green triballs, and 4 alliance coloured ones.
- Weight:  
Height: 6.18 Inches  
Diameter (at widest points) : 7 Inches  
Shape: Acorn Shaped  
Material: Plastic
- Movement is unpredictable.



# Understanding the Game Elements

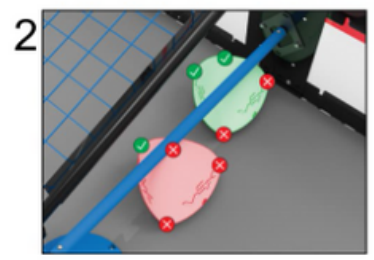
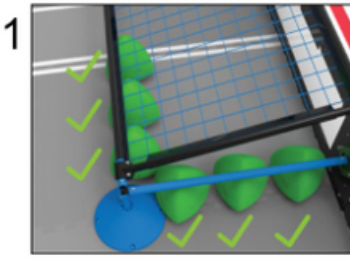
## Game Elements - Goals (and scoring)



- There are a total of 2 goals on the field: One red and one blue.
- The triball will not slide easily underneath the goal, since the goal is 5.78 inches high, whilst the triball is 6.18 inches tall.
- This means that the triball will require a small amount of force in order for it to fit underneath the goal.

Height: 5.78 inches  
Depth: 19.2 inches

The net prevents any launched triballs from landing in the goal area.

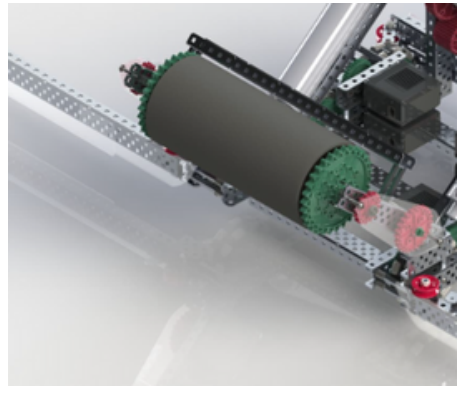
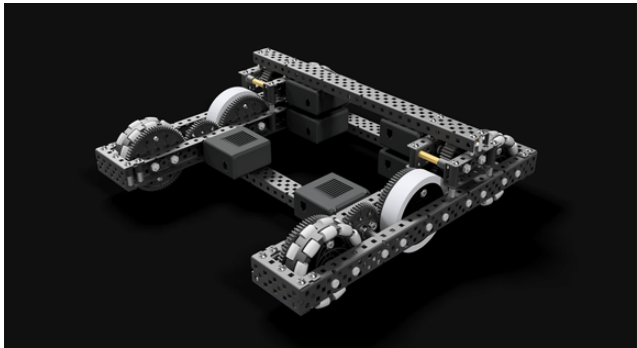


The triball is only counted as scored if TWO OR MORE "corners" of the triball have "broken the plane" of the pvc barriers of the goal.

This means that in diagram 2, the triballs are not considered scored since they do not have two corners breaking the plane of the pvc barrier

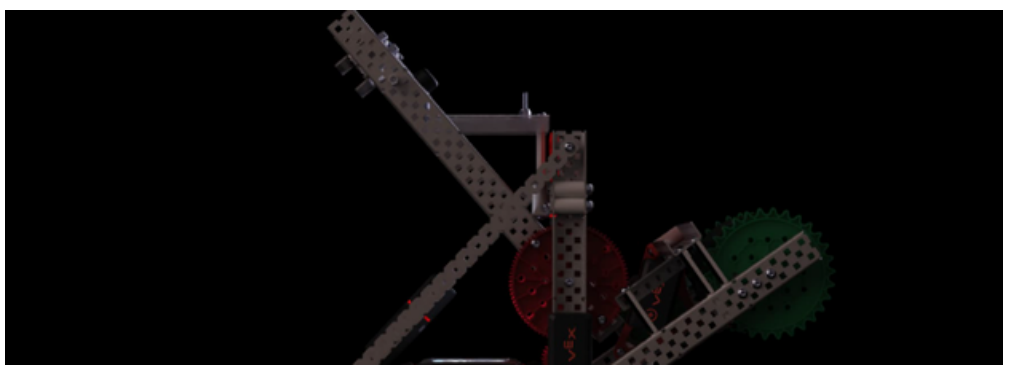
Although we weren't following the requirements of the 'client', the objectives of the game were still in question. We considered the aspects of the game and brainstormed which functionalities we should prioritise on our robot. We analysed each problem and ranked in terms of importance.

Our process is much the same. Researched-based, problem-centric design. We broke down the problem into 3 sections: the rapid **intake of tribals**, the targeted **dispersal of tribals**, all whilst **efficiently traversing the field**. Therefore we debated a few key robot design factors below.



A floating intake which lifts up to house the irregularly shaped triball

A drive train geared 48 to 84, giving us plenty of speed and talk to traverse the field well



A slapper with multiple slips on the rotation of the slip gear allows rapid firing of the triball. A platform that can ensure the consistency of each shot

# IDEATE/DESIGN

To ideate is to imagine or conceive a range of ideas combatting the problem while design is communicating these ideas through simple sketches

Karan emphasized the value of quickly generating ideas, advising against fixating on a single perfect design. Instead, he advocated for exploring multiple designs and developing the most promising ones. He underscored the necessity of thinking outside the box as the key to innovation, a sentiment that strongly resonates with our approach to forming ideas.



## Ideas for the Drivebase

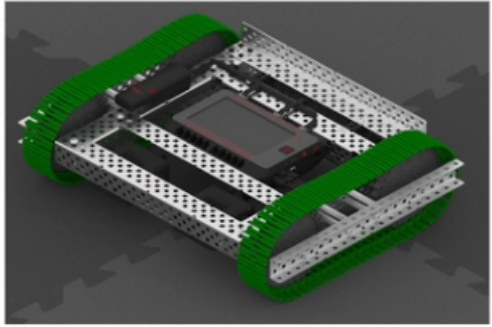


## Conclusion Of Analysis

Option 4 - Tank Tread Drive

The tank tread is also very less commonly used.

This drivebase utilises chains instead of traditional circular wheels.



[This picture is from the official vex website]

Tank Drive - Benefits

Very compact in size - makes it easier for the robot to fit within the size dimensions.



Relatively simple to build, with lots of online resources to aid with the building process.

Very customisable - allows the robot to be more fine tuned to the game strategy that we intend to go for.

We choose to go with the tank drive feeling that it met all of the criteria below which we defined as our musts.

**FAST:**

→ In the Over Under Game, the aim is to score as many triballs into goals as possible, so we need the robot to be able to move very rapidly in order to score as fast as possible. It is very compact in size and hence meets this criteria as it is lightweight.

**STRONG:**

→ During the game, our robot will most likely end up hitting other robots a lot of the time during the match, as well as slamming into goals and triballs throughout the match, so we need the drivebase to be able to withstand these impacts.

**DIMENSIONS**

→ The robot must fit inside the 18inch x 18inch maximum dimensions, so therefore we cannot have a drivebase any larger than this.

PROS	CONS
→ Ability to use screw joints and bearings, similar to a tank drive.	→ Cannot get over the middle PVC barrier due to the lack of solid wheels.
→ You can use motors in any position long the drivetrain, adding more customizability.	→ Has quite bad traction on wheels, making the robot susceptible to being pushed by other robots on the field.

This is our way of following Arup's process: considering lots of different designs, then having another team member evaluate the ideas in order to introduce a fresh perspective, so that we look through more than one lens.

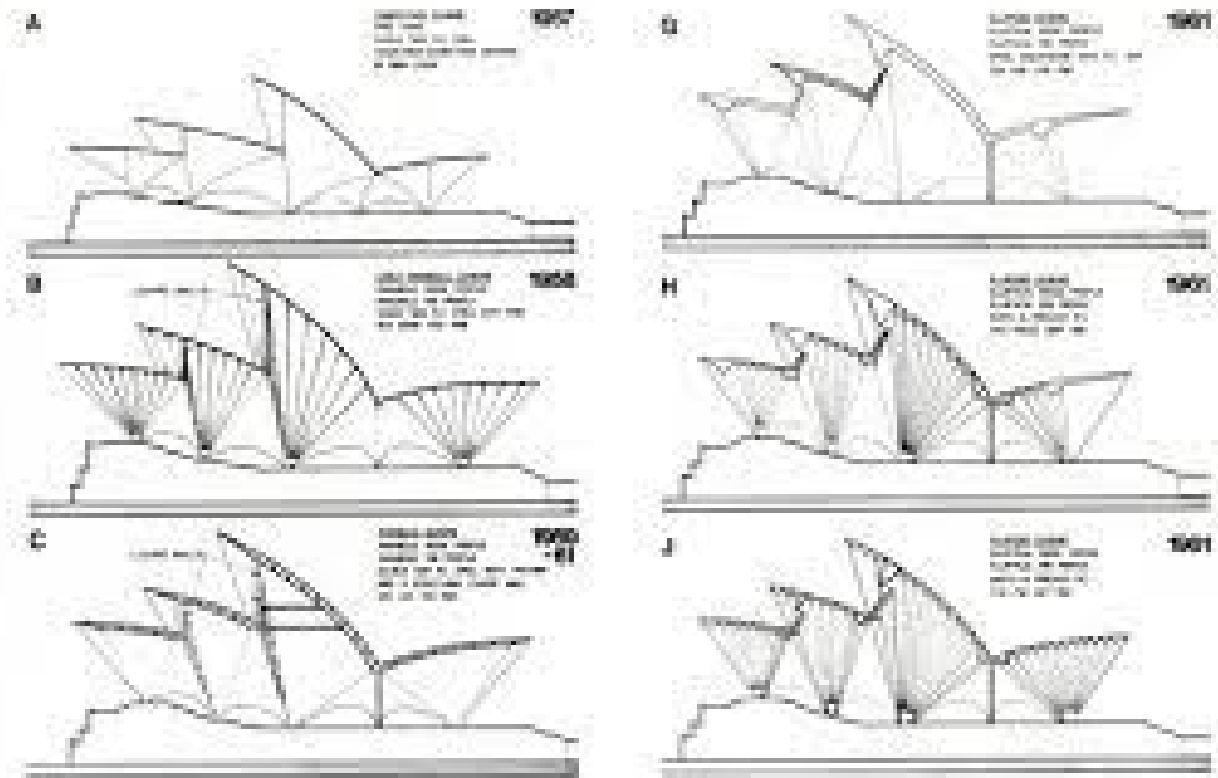


Rather of honing one product design, our ideating technique focuses on discovering the perfect one from a sea of others. As a result, we examine all of the alternative methods for solving the problem and discuss which are most likely to be more effective for this particular game specifications



Arup ensures that each part of the problem is broken down an the best solution for each problem is created for the client. This is further demonstrated below

# ARUP'S TRIAL SCHEMES



## Case Study: Sydney Opera House

In the diagram above, you can see a few of the diagrams drawn by the design trial schemes, which show how each of the trial schemes came up with different ideas, each with different flaws and advantages. with different flaws and advantages.

Karan's analysis of ARUP's impact on architecture and problem-solving method revealed that, for the Sydney Opera House, the business investigated 12 trial concepts, each describing a different design for the distinctive roof. They chose the spherical solution and installed ten roof sails made of 75-meter-diameter sphere parts. This emphasises the necessity of varied perspectives in both large and small-scale projects, which prevents ideas from being suppressed. ARUP's use of focused trial schemes allowed them to widen their solutions, promoting unique and inventive problem-solving approaches.





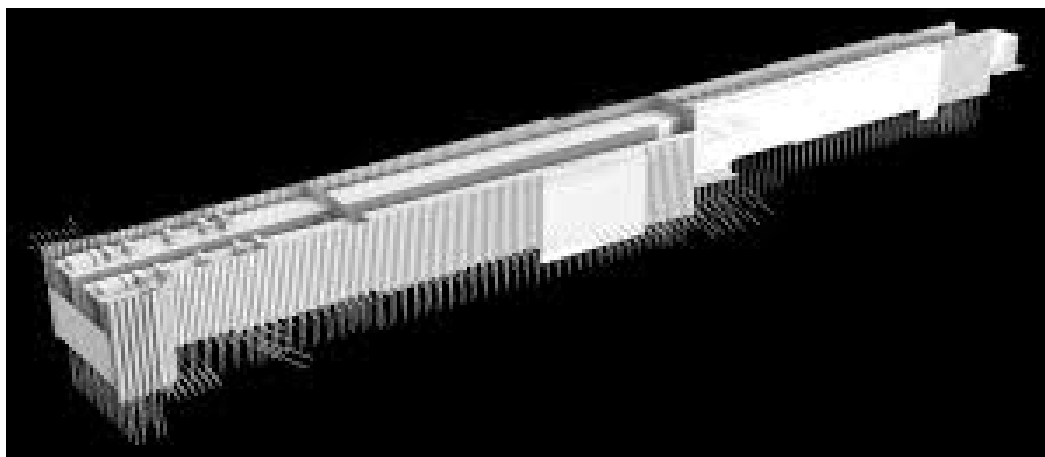
# VISUALISE

To help conceptualize an idea, making it much more tangible to envisage or the creation of preliminary versions of a product from a design.



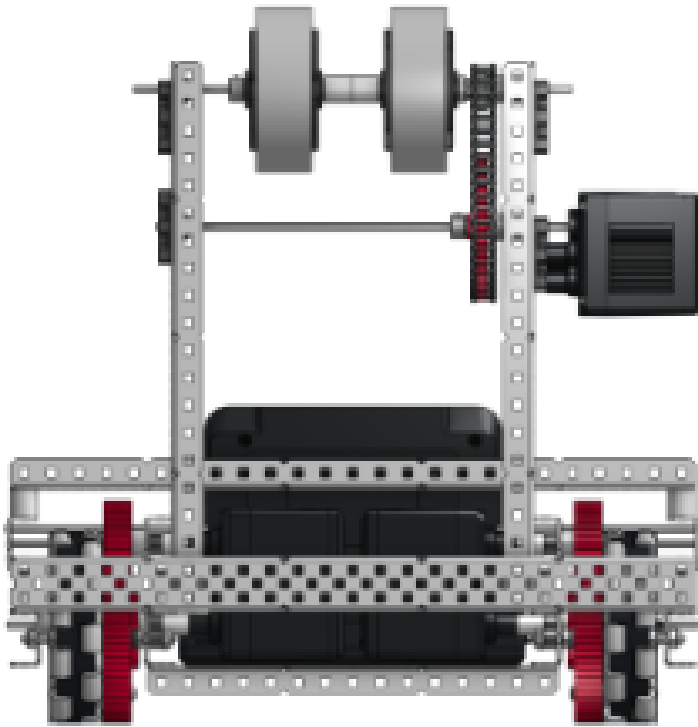
We employ stress testing (similar to how Arup uses tools such as HOLO-BIM for seismic testing), but instead of modelling pressures on a building's structural integrity, we simulate match scenarios like defence to check that the robot is robust enough to survive impact. We also test different robot mechanisms to guarantee that they perform consistently and without defects. This helps us to discover any issues with the robot and determine how to iterate the design and correct our mistakes.

[//www.arup.com/news-and-events/arup-presented-the-highest-award-in-building-information-modelling-bim-excellence](http://www.arup.com/news-and-events/arup-presented-the-highest-award-in-building-information-modelling-bim-excellence)

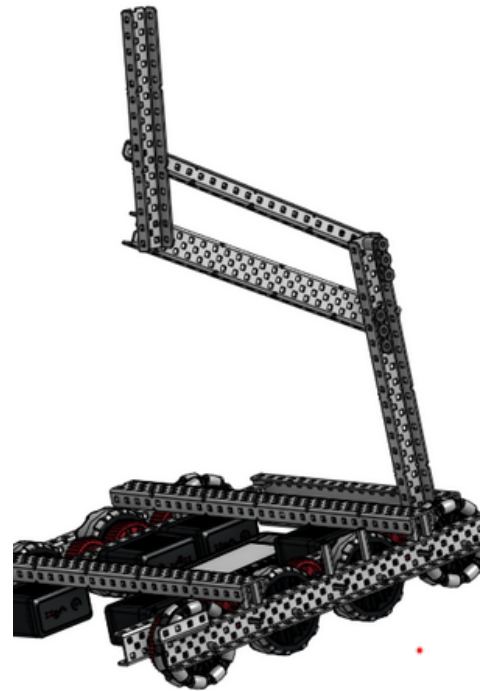


# CAD

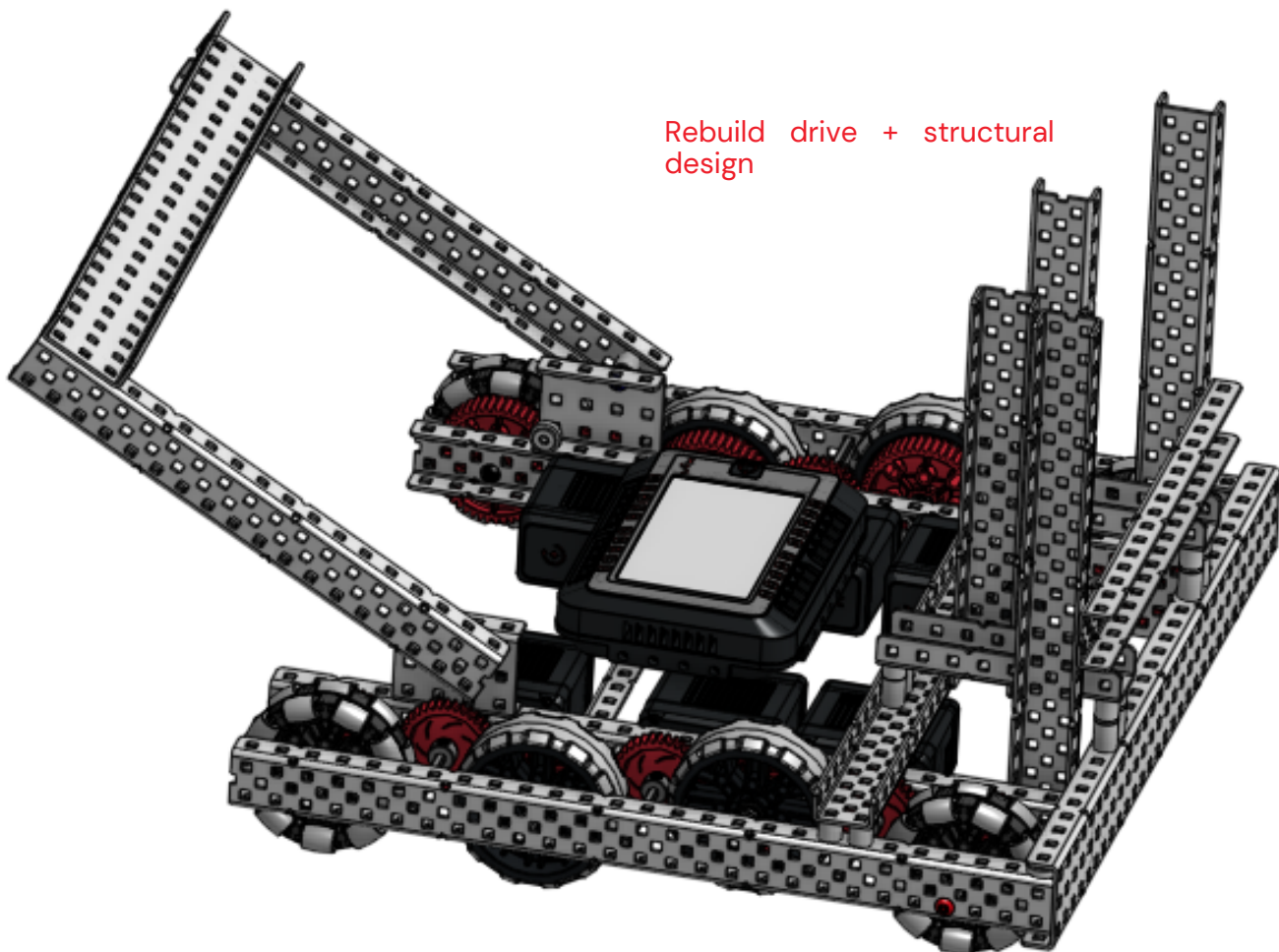
Visualisation is extremely important to our final outcomes. We took advantage of onshape, a unique CAD software to point out any flaws and issues with the current design without blindly going into the building process. This benefited our progress in many ways.



Flywheel



Drive + 4 bar lift prototype



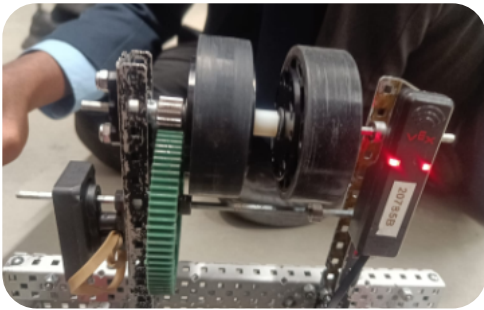
Rebuild drive + structural design

# TEST

To test is to scrutinize the strengths and weaknesses of a product by putting it under strain. To iterate is to intergrate the feedback from testing to create several improved versions of the same product.

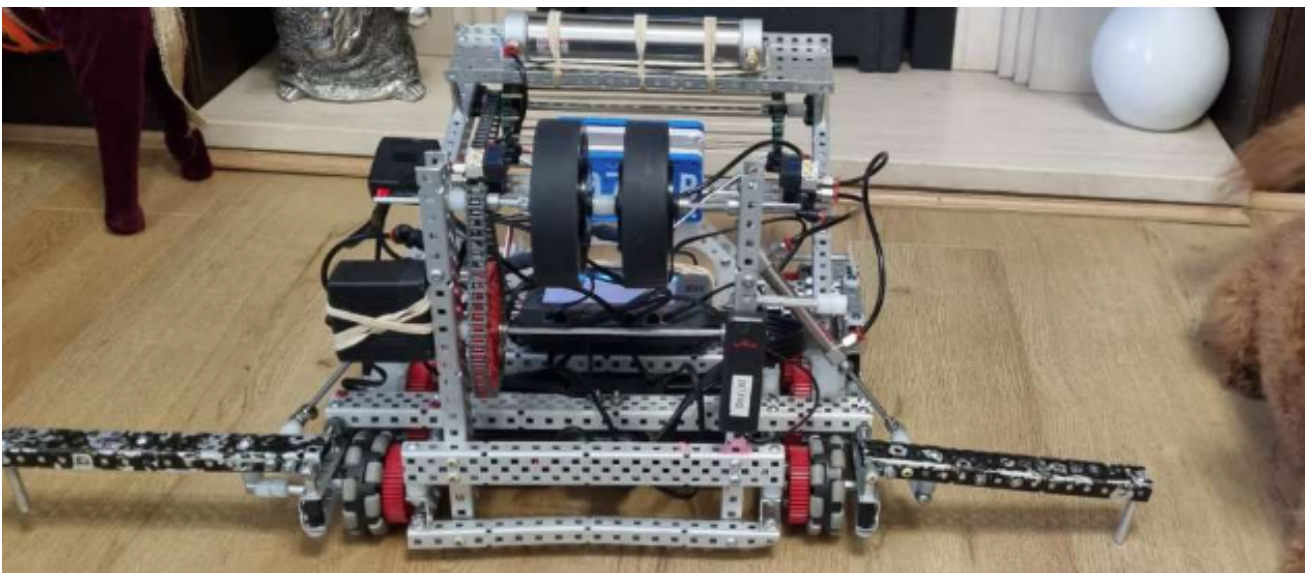
Testing is critical in architecture; with thousands of people and stakeholders relying on Arup to deliver, there is no room for unforeseen errors. As a result, before handover, they must do risk assessments and building performance analyses, as well as test each of their projects against simulated scenarios.

We employ stress testing (similar to how Arup uses tools such as HOLO-BIM for seismic testing), but instead of modelling pressures on a building's structural integrity, we simulate match scenarios like defence to check that the robot is robust enough to survive impact. We also test different robot mechanisms to guarantee that they perform consistently and without defects. This helps us to discover any issues with the robot and determine how to iterate the design and correct our mistakes.



Whilst testing the flywheel we noticed that the triballs werent being launched as far as was required. We concluded this was due to the turning effect about the axel was too low, allowing us to decide our next iteration.

We initially had two mechanisms in mind for the sleds aluminium gussets and Versa hubs. Unfortunately through field testing, we found both methods were unsuccessful as they either were too low or had a too flat of an arc (in that order)

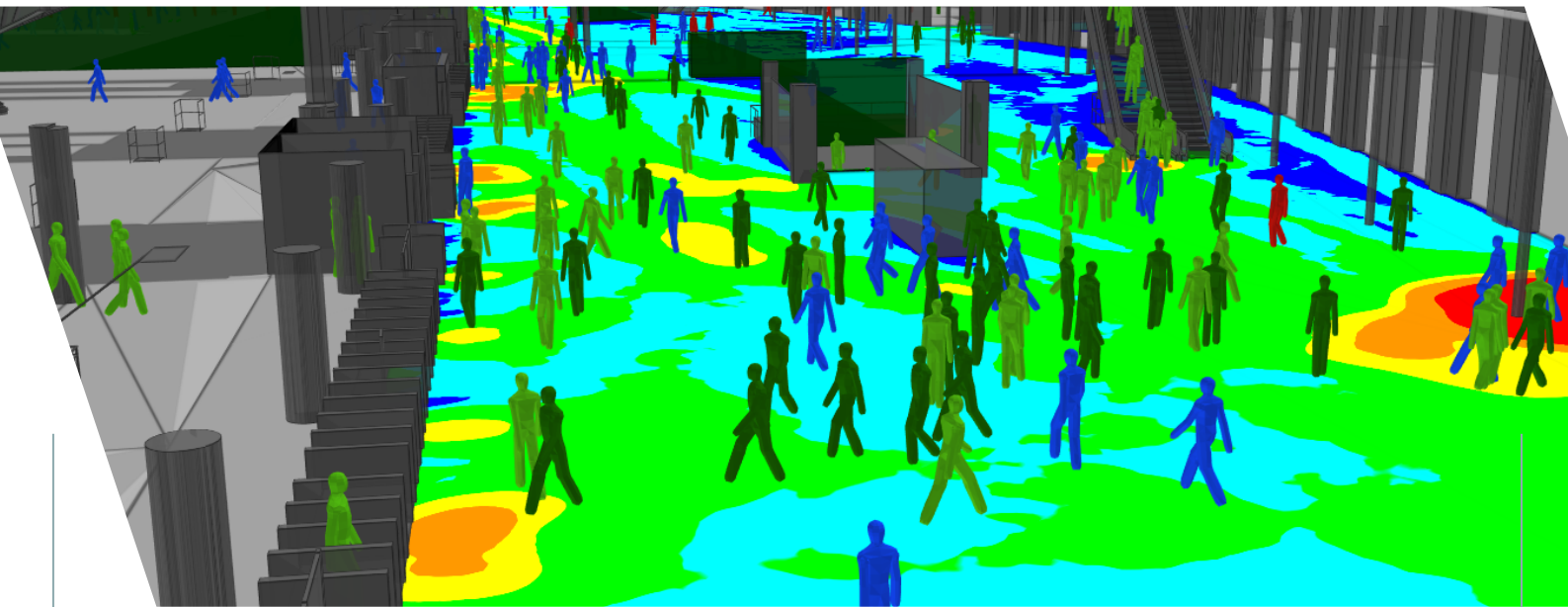


We also tested our wing mechanism, as you can see a key problem was the right wing making contact with the floor which would cause driving difficulty. Therefore we added a simple stopping mechanism which would hit the drive before the wing hit the floor.

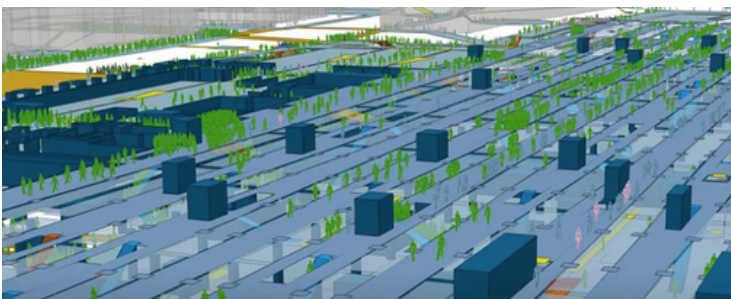


# ARUP DESIGN TESTING

Arup is a key player in the construction of public transport facilities. Therefore it is key to understand how their design would function as a convenient spacious and aesthetic design for the public as shown here.



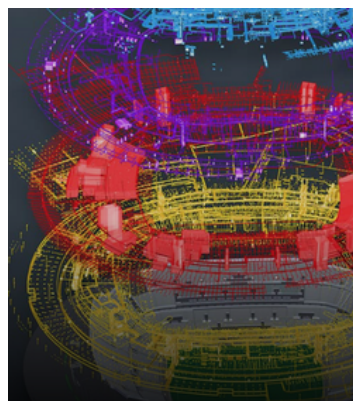
Consequently, Karan mentioned that due to this they focus on the use of simulation softwares to try and visualize their designs. ARUP decided to use Oasys Mass Motion, crowd simulation software, an industry leading and award winning program used by engineers and architects across the globe.



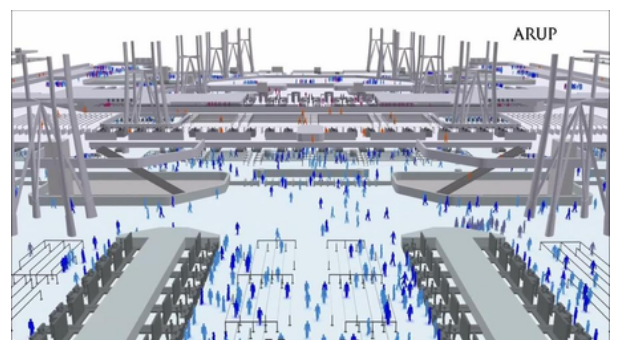
THE TORONTO UNION STATION - CROWD SIMULATION - HIGHLIGHTED ALL FLAWS WITH DESIGN ROUTES AND ANY CONGESTION FORMED

## TOUYON INTERNATIONAL AIRPORT TERMINAL 3

A 3D SIMULATION MODEL IN A COLLISION AVOIDANCE - AN ENVIRONMENT TO FULLY ASSESS THE PROPOSED PERFORMANCE OF TERMINAL 3. THE PASSENGER JOURNEY WAS VISUALISED AND DESIGNED IN DETAILED.



THE LAYERS OF AS ROMA STADIUM- THE ENERGY EFFICIENT COLLOSEUM - INCORPORATING THE INDUSTRIES MOST SUSTAINABLE TECHNOLOGY TO HOUSE 60,000



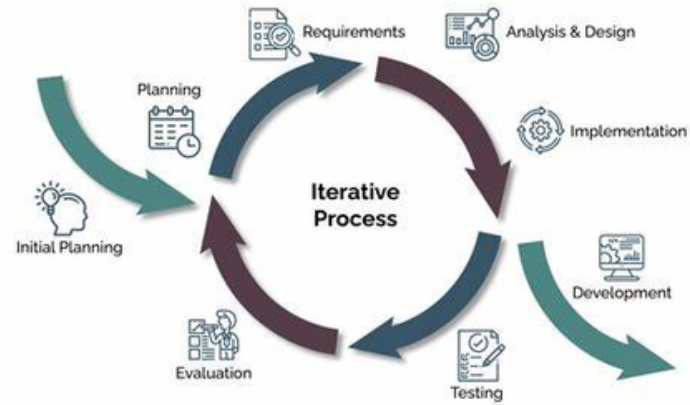


# ITERATION

We believe in rapid iteration, drastically improving the overall build quality and features of our robot through rigorous testing. We maintained a constant cycle of improvement which allows us to create the very best vrc program.



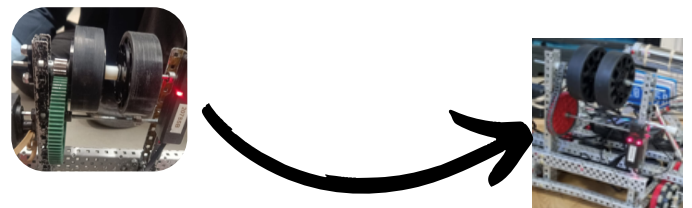
Iterative Process Model



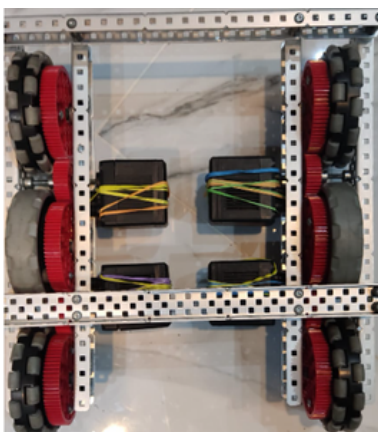
The final AR generation/iteration of the Milan carbon-neutral project



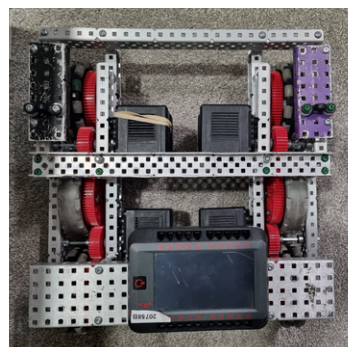
New more effective delrin sleds



Sprocket flywheel (more effective than a geared flywheel) + Larger wheels means larger force (moments)

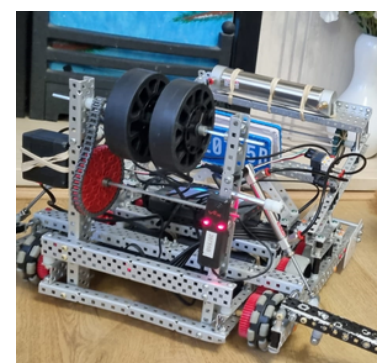


Coventry Regional



QE Regional

Now



# HOW VEX HAS HELPED US?

VEX has tremendously helped us, making us more equipped to work in small teams in a professional and organized while also also instilling us with importance of design iteration.

Critical thinking - the ability to analyze, evaluate and reason are essential in careers, and this is exactly what VEX forces to help challenge complex engineering problems

It is essential in careers to to effectively communicate to share and promote ideas while closely working with your team to create thoughtful and holistic solutions. VEX instills close teamwork in all

To progress in a career, it is essential to come up with new ideas and products, exactly which is what VEX forces us to do. VEX forces one to think about new ways of challenging an evolving problem.

Willing to consider new ideas without being prejudiced to help come up with better products is key in both VEX and in careers, both in STEM/engineering but also other careers

