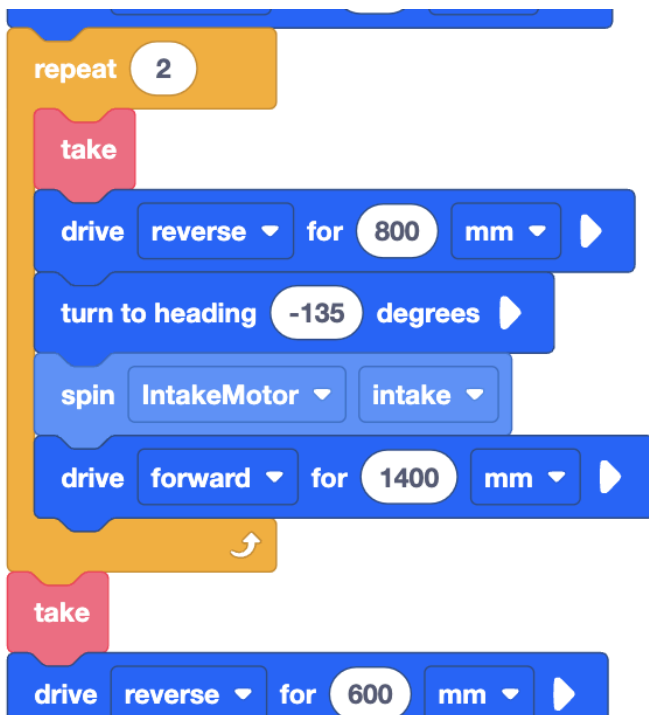


The top right corner is function/my block of take

We can reuse it





The image shows a sequence of Scratch code blocks for controlling a robot arm. The blocks are as follows:

- spin IntakeMotor intake
- spin ArmMotor to position 1200 degrees and don't
- drive forward for 1200 mm
- wait 0.5 seconds
- turn to heading 130 degrees
- drive forward for 800 mm
- turn to heading 90 degrees
- spin IntakeMotor outtake

Minimising the lifting of robot arm